

Prior sensitivity analysis in default Bayesian structural equation modeling

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Bayesian Structural Equation Modeling (BSEM)

Classical SEM

SEMs offer a good representation of substantive theories.

However..

- Nonconvergence
- Inadmissible solutions
- Large number of groups
- Computationally inconvenient

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Bayesian SEM thought to solve these problems.

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Prior specification is important, but difficult.

Reliance on *default* priors.

Question

Do all default priors perform similarly in BSEM?

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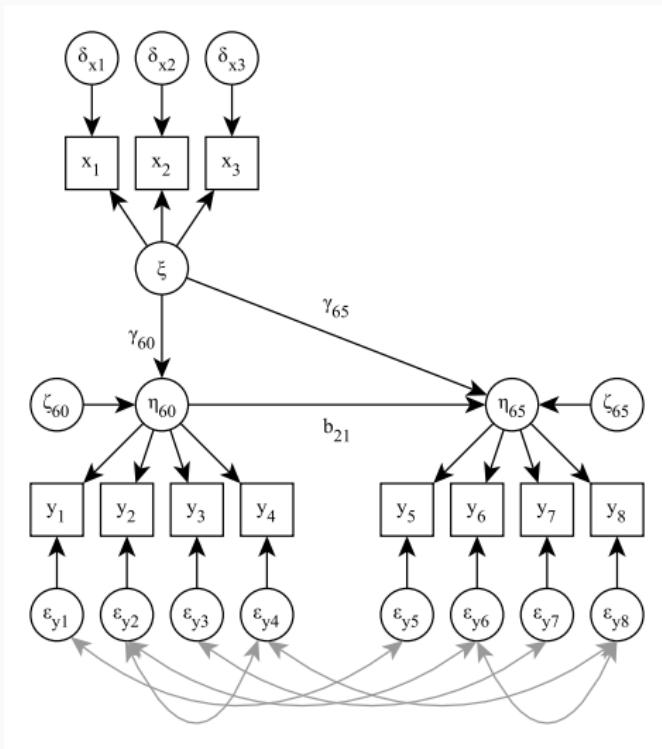
Question

Do all default priors perform similarly in BSEM?

Answer

No! So conduct prior sensitivity analyses!

Model



Priors

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We consider three types of default priors:

1. Noninformative improper priors
2. Vague proper priors
3. Empirical Bayes priors

Noninformative improper priors

- $p(\sigma^2) \propto \sigma^{-2}$ implemented as inverse Gamma(0, 0)
- $p(\sigma^2) \propto \sigma^{-1}$ implemented as inverse Gamma($-\frac{1}{2}, 0$)
- $p(\sigma^2) \propto 1$ implemented as inverse Gamma(-1, 0) (Mplus default)

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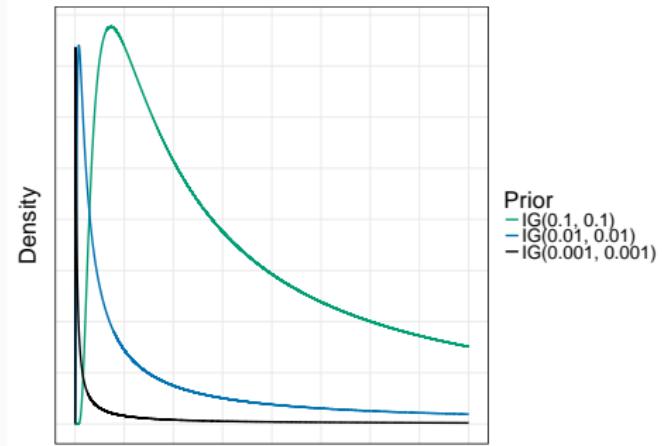
Problem: can result in improper posteriors

Vague proper priors

Variances: approximate

$$p(\sigma^2) \propto \sigma^{-2}$$

- inverse Gamma(.001, .001)
(WinBUGS default)
- inverse Gamma(.01, .01)
- inverse Gamma(.1, .1)

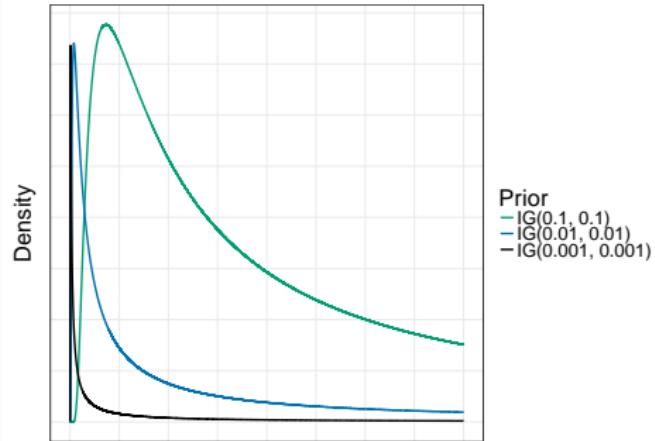


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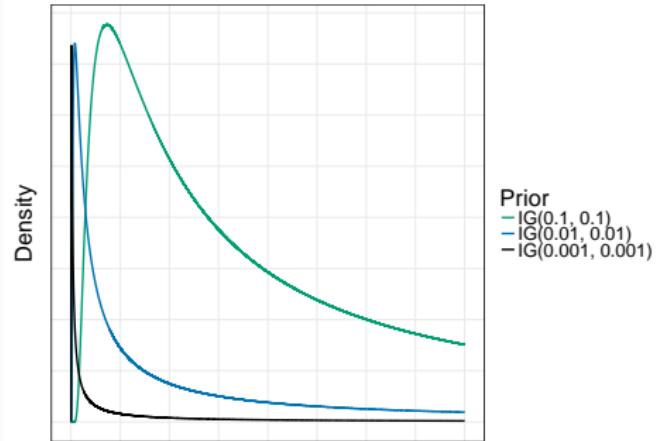
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- Normal(0, 1000) & Normal(0, 100) (Blavaan default)

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Problem: choice of hyperparameters can arbitrarily influence the results.

Empirical Bayes priors

Variances: inverse Gamma $\left(\frac{1}{2}, \hat{\sigma}^2 \cdot Q^{-1}\left(\frac{1}{2}, \frac{1}{2}\right)\right)$

- Information of one data point
- Median equals ML estimate

Empirical Bayes priors

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Location parameters: Normal($0, \hat{\mu}^2 + \hat{\sigma}^2$)

- e.g. Normal($0, \hat{\nu}_y^2 + \hat{\sigma}_y^2$)
- Minimal information
- Positive support where the likelihood is concentrated

Simulation study

Data generating conditions

- Political democracy and industrialization model
- $N \in \{35, 75, 150, 500\}$
- Population values equal to ML estimates
- Varied population values for: $\gamma_{65}, \gamma_{60}, \lambda_{y4}, \lambda_{y8}, \Omega_D$
- Analyzed with the different default priors & ML

Results

- *Convergence:* Nonconvergence for $\pi(\sigma^2) \propto \sigma^{-2}$

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Conclusion

Performance of default priors varies greatly across conditions and outcomes. Important to conduct a prior sensitivity analysis.

Prior Sensitivity Analysis

Steps

1. Decide which parameters to investigate
2. Decide which priors to include
3. Technical implementation
4. Interpretation of the results:
no differences; differences between informative & default; differences
between all priors.

Conclusions

Conclusions

- BSEM is useful and popular
- Prior specification can be difficult
- “Default” priors vary in performance
- Prior sensitivity analysis is essential
- More robust priors should be used (or better EB priors?)

Questions?

Paper: <http://dx.doi.org/10.1037/met0000162>

Code prior sensitivity analysis:

<http://dx.doi.org/10.1037/met0000162.supp>

Preprint: <https://osf.io/zt8e9/>

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Model

The structural model (for $i = 1, \dots, n$) is given by:

$$\boldsymbol{\eta}_i = \boldsymbol{\alpha} + \boldsymbol{B}\boldsymbol{\eta}_i + \boldsymbol{\Gamma}\boldsymbol{\xi}_i + \boldsymbol{\zeta}_i \quad \text{with } \boldsymbol{\xi}_i \sim N(\boldsymbol{\mu}_{\xi}, \boldsymbol{\omega}_{\xi}^2), \\ \text{and } \boldsymbol{\zeta}_i \sim N(\mathbf{0}, \boldsymbol{\Omega}_{\zeta})$$

The measurement model is given by:

$$\mathbf{y}_i = \boldsymbol{\nu}_y + \boldsymbol{\Lambda}_y \boldsymbol{\eta}_i + \boldsymbol{D}_i + \boldsymbol{\epsilon}_i^y \quad \text{with } \boldsymbol{D}_i \sim N(\mathbf{0}, \boldsymbol{\Omega}_D), \\ \text{and } \boldsymbol{\epsilon}_i^y \sim N(\mathbf{0}, \boldsymbol{\Sigma}_y) \\ \mathbf{x}_i = \boldsymbol{\nu}_x + \boldsymbol{\Lambda}_x \boldsymbol{\xi}_i + \boldsymbol{\delta}_i^x \quad \text{with } \boldsymbol{\delta}_i^x \sim N(\mathbf{0}, \boldsymbol{\Sigma}_x)$$

Data generating conditions

Variable	Levels	Specifications
Sample size	4	$N \in \{35, 75, 150, 500\}$
Direct effect	3	$\gamma_{65} = 0$ $\gamma_{65} = 1$ $\gamma_{65} = 2$
Indirect effect	3	$\gamma_{60} \times b_{21} = 0 \times 0.837$ $\gamma_{60} \times b_{21} = 1 \times 0.837$ $\gamma_{60} \times b_{21} = 2 \times 0.837$
Loadings	3	$\lambda_{y4} = \lambda_{y8} = 0$ $\lambda_{y4} = \lambda_{y8} = 1$ $\lambda_{y4} = \lambda_{y8} = 2$
Error covariances	2	$\Omega_D = 0$ $\Omega_D = 1$

Analysis conditions

Prior type	Prior specification
Noninformative improper	$\pi(\sigma^2) \propto 1$ & $N(0, 10^{10})$ $\pi(\sigma^2) \propto \sigma^{-1}$ & $N(0, 10^{10})$ $\pi(\sigma^2) \propto \sigma^{-2}$ & $N(0, 10^{10})$
Vague proper	$IG(.001, .001)$ & $N(0, 10^{10})$ $IG(.01, .01)$ & $N(0, 10^{10})$ $IG(.1, .1)$ & $N(0, 10^{10})$
Vague normal:	$N(0, 1000)$ & $N(0, 100)$ & $\pi(\sigma^2) \propto 1$
Empirical Bayes	
EB1:	$IG\left(\frac{1}{2}, \hat{\sigma}^2 * Q^{-1}\left(\frac{1}{2}, \frac{1}{2}\right)\right)$ & $N(0, \hat{\mu}^2 + \hat{\sigma}^2)$
EB2:	$\pi(\sigma^2) \propto 1$ & $N(0, \hat{\mu}^2 + \hat{\sigma}^2)$